

## **Shock Absorber**

## Series RB/RBL/RBQ

## **Absorbing impact** and noise

Dampening to meet the high speed requirements of the modern world.

Shock absorber: Series RB Coolant resistant type: Series RBL

Usable without a stopper nut The strong body can be positioned directly.

## **Short type: Series RBQ**

A compact style that has been shortened lengthwise

Allowable eccentric angle is 5° Suitable for absorption of rotation energy.

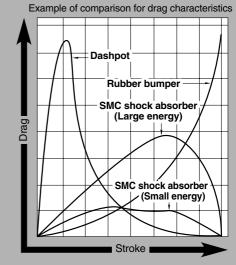
Usable without a stopper nut The strong body can be positioned directly.



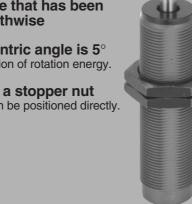
## Shock absorber

Automatic adjustment to the appropriate absorption performance

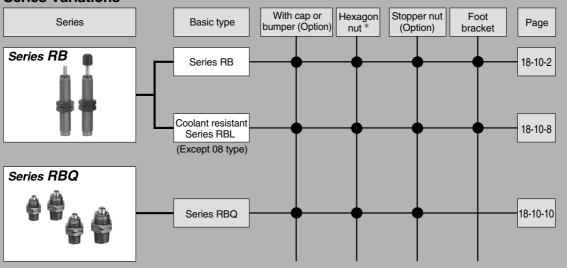
Specially designed orifice can absorb energy comprehensively and most appropriately in many different applications. This ranges from high speed low loads, to load speed high loads; without requiring additional adjustment of the shock absorber.



\* Drag waveform will vary depending on the operating conditions.



#### **Series Variations**



2 Hexagon nuts are attached for Series RB and standard models RBQ.

RE A

**REC** C

**C**□Y

MQ M

**RHC** 

MK(2)

RS G

RS<sup>H</sup>

**RZQ** 

MI®

CEP1

CE1

CE2

ML2B

C<sub>0</sub>5-S

CV MVGQ

CC

RB

J

D-

-X

20-

Data



## **Shock Absorber** Series RB

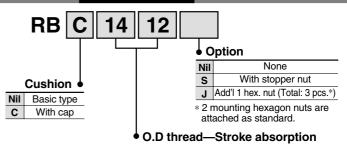
## **Specifications**

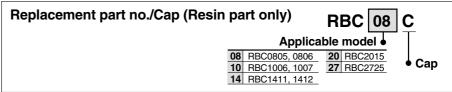
Model	Basic type	RB0805	RB0806	RB1006	RB1007	RB1411	RB1412	RB2015	RB2725
Specifications	With cap	RBC0805	RBC0806	RBC1006	RBC1007	RBC1411	RBC1412	RBC2015	RBC2725
Max. energy abs	sorption (J)	0.98	2.94	3.92	5.88	14.7	19.6	58.8	147
Stroke absorpt	tion (mm)	5	6	6	7	11	12	15	25
Collision spe	ed (m/s)				0.05	to 5.0			_
Max. operating fr (cycle/min)	requency *	80	80	70	70	45	45	25	10
Max. allowable	thrust (N)	245	245	422	422	814	814	1961	2942
Ambient temperatur	re range (°C)	-10 to 80 (No freezing)							
Spring force	Extended	1.96	1.96	4.22	4.22	6.86	6.86	8.34	8.83
(N)	Retracted	3.83	4.22	6.18	6.86	15.30	15.98	20.50	20.01
\\\a:\a\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\	Basic type	15	15	23	23	65	65	150	350
Weight (g)	With cap	16	16	25	25	70	70	165	400

<sup>\*</sup> It denotes the values at the maximum energy absorption per one cycle. Max. operation cycle/min can increase in proportion to energy absorption.



## **How to Order**



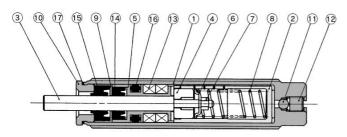


Cap cannot be mounted for basic type. Please place an order with cap type from the beginning.

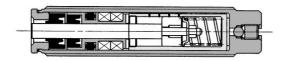
## Construction

Basic type

## **Extended**



#### Compressed



#### **Component Parts**

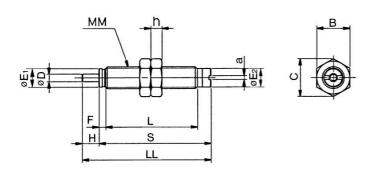
No.	Description	Material	Treatment
1	Outer tube	Rolled steel	Gray coated
2	Inner tube	Special steel	Heat treated
3	Piston rod	Special steel	Electroless nickel plated
4	Piston	Special steel	Heat treated
(5)	Bearing	Special bearing material	
6	Spring guide	Carbon steel	Zinc chromated
7	Lock ring	Copper	
8	Return spring	Piano wire	Zinc chromated
9	Seal holder	Copper alloy	
10	Stopper	Carbon steel	Zinc chromated
11)	Steel ball	Bearing steel	
12	Set screw	Special steel	
13	Accumulator	NBR	Foam rubber
14)	Rod seal	NBR	
15)	Scraper	NBR	
16	Gasket	NBR	
17)	Gasket	NBR	Only RB(C)2015, 2725



## Shock Absorber Series RB

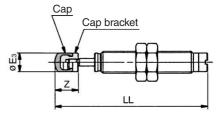
## **Dimensions**

Basic type: RB0805, RB0806, RB1006, RB1007



#### With cap: RBC0805, RBC0806 RBC1006, RBC1007

\* Other dimensions are the same as the basic type.



RE A

**REC** 

**C**□X

**C**□Y

MQ M

**RHC** 

MK(2)

RS<sub>G</sub>

RS<sup>H</sup>

**RZQ** MIS

CEP1

CE1

CE<sub>2</sub>

ML2B

C<sub>G</sub>5-S

CV

MVGQ

CC RB

J

D-

-X

20-

Data

## **Replacement Parts**

R

19

19

27

36

Hexagon nut

C

21.9

21.9

31.2

41.6

h

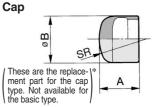
6

6

6

6





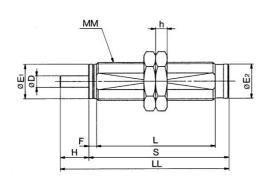
Material: Polyurethane

Dimensions						
Α	В	SR				
6.5	6.8	6				
9	8.7	7.5				
12.5	12	10				
16	18	20				
21	25	25				
	A 6.5 9 12.5 16	A         B           6.5         6.8           9         8.7           12.5         12           16         18				

(mm)

Mo	del	Basic type dimensions				With cap*			Hexagon nut								
Basic type	With cap	D	E <sub>1</sub>	E <sub>2</sub>	F	Н	а	L	LL	MM	S	E₃	LL	Z	В	C	h
RB0805	RBC0805	2.8	6.8	6.8	2.4	5	1.4	33.4	45.8	M8 x 1.0	40.8	6.8	54.3	8.5	12	13.9	4
RB0806	RBC0806	2.8	6.8	6.8	2.4	6	1.4	33.4	46.8	M8 x 1.0	40.8	6.8	55.3	8.5	12	13.9	4
RB1006	RBC1006	3	8.8	8.6	2.7	6	1.4	39	52.7	M10 x 1.0	46.7	8.7	62.7	10	14	16.2	4
RB1007	RBC1007	3	8.8	8.6	2.7	7	1.4	39	53.7	M10 x 1.0	46.7	8.7	63.7	10	14	16.2	4

Basic type: RB1411, RB1412, RB2015, RB2725



D

5

5

6

8

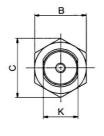
Εı

12.2

12.2

18.2

25.2



Basic type dimensions

K

12

12

18

25

58.8

58.8

62.2

86

ММ

M14 x 1.5

M14 x 1.5

M20 x 1.5

M27 x 1.5

11

78.3

79.3

88.2

124

S

67.3

67.3

73.2

99

F

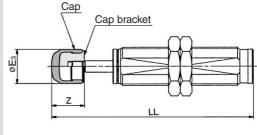
12

12

18

25

### With cap: RBC1411, RBC1412 RBC2015, RBC2725 \* Other dimensions are the same as the basic type.



With cap\*

91.8 13.5

92.8

147

105.2 17

7

13.5

23

ш

RB2015	RBC2015
RB2725	RBC2725

**Hexagon Nut** 

Basic type

RB1411

**RB1412** 

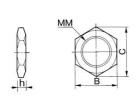
(2 pcs. standard equipment)

Model

With cap

RBC1411

**RBC1412** 



()								
Part no.	Dimensions							
ranino.	MM	h	В	С				
RB08J	M8 x 1.0	4	12	13.9				
RB10J	M10 x 1.0	4	14	16.2				
RB14J	M14 x 1.5	6	19	21.9				
RB20J	M20 x 1.5	6	27	31.2				
RB27J	M27 x 1.5	6	36	41.6				

## **Option**

E2

12

12

18

25

F

3.5

3.5

4

5

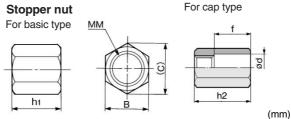
Н

11

12

15

25



								()			
Par	t no.		Dimensions								
Basic type	With cap	В	С	h1	h2	ММ	d	f			
RB08S	RBC08S	12	13.9	6.5	23	M8 x 1.0	9	15			
RB10S	RBC10S	14	16.2	8	23	M10 x 1.0	11	15			
RB14S	RBC14S	19	21.9	11	31	M14 x 1.5	15	20			
RB20S	RBC20S	27	31.2	16	40	M20 x 1.5	23	25			
RB27S	RBC27S	36	41.6	22	51	M27 x 1.5	32	33			

10-18-3

(mm)

## Series RB/Shock Absorber **Technical Data:**

## Model Selection

## **Model Selection Step**

## 1. Type of impact

- Cylinder stroke at load (Horizontal)
- Cylinder stroke at load (Downward)
- Cylinder stroke at load (Upward) ■ Conveyor stroke at load (Horizontal)
- Free horizontal impact
- Free dropping impact
- Rotating impact (With torque)

#### 2. Enumeration of operating conditions

Symbol		
m	Impacting object weight	kg
υ	Collision speed	m/sec
h	Dropping height	m
ω	Angle speed	rad/sec
r	Distance between axis of cylinder and impact point	m
d	Bore size	mm
р	Cylinder operation pressure	MPa
F	Thrust	Ν
T	Torque	N⋅m
n	Operation cycle	cycle/min
t	Ambient temperature	ô
μ	Friction coefficient	_

3. Specifications and operational instructions Ensure that the collision speed, thrust, operation cycle, the ambient temperature and atmosphere fall within the specifications. \*Be aware of the min. installation radius in the case of rotating impacts.

Calculation of kinetic energy E<sub>1</sub> Using the equation suitable for the classification of impact.

In the case of cylinder stroke at load and free horizontal impact. substitute respective figures for Data A in order to calculate E1.

5. Calculation of thrust energy E2 Select any shock absorber as a provisional

In the case of thrust energy of cylinder E1, substitute respective figures for Data B or Data C.

6. Calculation of corresponding weight of impacting object Me Absorbed energy  $E = E1 + E_2$ Corresponding weight of impacting object  $Me = \frac{2}{800} \cdot E$ 

Substitute both absorbed energy E and collision speed  $\upsilon$  for Data A in order to calculate the corresponding weight of the impacting object.

## 7. Selection of applicable model

Taking into consideration the corresponding weight of the impacting object Me, calculated using Data D and collision speed v, check provisional model compatibility with the condition of application. If this is satisfactory, then the said provisional model will be the

## **Caution on Selection**

In order for the shock absorbers to operate accurately for long hours, it is necessary to select a model that is well-suited to your operating conditions. If the impact energy is smaller than 5% of the maximum energy absorption, select a model that is one class

## Selection Example

	Cylinder stroke at load (Horizontal)
1	Shock absorber
Type of impact	Cylinder Cylinder
Collision speed (1)	υ
Kinetic energy	$\frac{1}{2}$ ·m· $v^2$

Thrust energy E2	F₁⋅S
Absorbed energy E	E <sub>1</sub> + E <sub>2</sub>
Corresponding (2) weight of impacting object	<u>2</u> <del>0</del> <sup>2</sup> ⋅ E

Dperating conditions	0 = 0.3 m/s d = 40 mm p = 0.5 MPa n = 20 cycle/min t = 25°C

m = 50 kg

Specifications and operational | F ... F1 ... 628 < 1961 (max.) instructions

Thrust energy

 Confirmation of specifications υ ··· 0.3 < 5 (max.) t ··· –10 (min.) < 25 < 80 (max.)

Calculation of kinetic energy E<sub>1</sub>

• Kinetic energy E<sub>1</sub> Use Formula to calculate E1. Substitute 50 for m and 0.3 for  $\upsilon$ .

Calculation of thrust energy E2

● Thrust energy E2 Provisionally select a model RB2015 and make the use of Data B. According to d = 40, E2  $E_2\cong 9.4\ J$ 

## Calculation of weight of impacting object Me

Corresponding weight of impacting object Me

corresponding Use the formula "Absorbed energy  $E = E_1 + E_2 = 2.3 + 9.4 = 11.7 J$ " to calculate Me. Substitute 11.7 J for E and 0.3 for  $\upsilon$ . Me ≅ 260 kg

## Selection of

 Selection of applicable model According to Data D, the tentatively selected RB2015 satisfies Me = 260 kg < 400 kg at v = 0.3. Ultimately, it will result in an operating frequency of n···20 < 25, without causing a problem. applicable model

**SMC** 

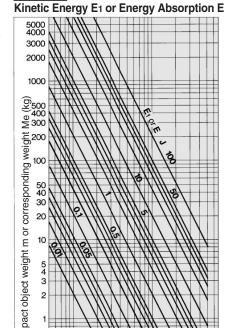
## Select RB2015

#### 1. Type of Impact

	Cylinder stroke at load (Downward)	Cylinder stroke at load (Upward)	Conveyor stroke at load (Horizontal)	Free dropping impact	Rotating impact (Weight torque)	
Type of impact	Cylinder Load v	υ Load m Cylinder		Load v	"   "   "   "	
Collision speed (1)	υ	υ	υ	$\sqrt{2 \text{ gh}}$	ω·R	
Kinetic energy E <sub>1</sub>	$\frac{1}{2}$ ·m· $v^2$	$\frac{1}{2}$ ·m· $v^2$	$\frac{1}{2}$ ·m· $v^2$	m⋅g⋅h	$\frac{1}{2}$ ·I· $\omega^2$	
Thrust energy E2	F <sub>1</sub> ·S + m·g·S	F₁⋅S – m⋅g⋅S	m⋅g⋅μ⋅S	m⋅g⋅S	T. S R	
Absorbed energy E	E <sub>1</sub> + E <sub>2</sub>	 E <sub>1</sub> + E <sub>2</sub>	E <sub>1</sub> + E <sub>2</sub>	E <sub>1</sub> + E <sub>2</sub>	E <sub>1</sub> + E <sub>2</sub>	
Corresponding (2) weight of impacting object	<u>2</u> . <sub>E</sub>	 $\frac{2}{v^2}$ E	<u>2</u> , E	$\frac{2}{v^2}$ E	$\frac{2}{v^2}$ E	
		Note 2) An "Impact bod	v eguivalent weight" is t	ne weight of an impact	object without involving	

Note 1) Collision speed is momentary velocity at which object is impacting against shock

## Data A



0.2 0.3 0.40.5

Collision speed υ (m/s)

thrust, into which an object's total energy has been converted.), refer to the catalog of

Data C

Thrust Energy at Load m.g.s

Note 3) For the formula of moment of inertia I (kg·m²), refer to the catalog of rotary actuator.

#### (Operating pressure 0.5 MPa) Data B Thrust Energy of Cylinder F1-S

rotary actuator. Hence,  $E = \frac{1}{2} \cdot Me \cdot V^2$ 

N	1odel		RB□0806 RB□1006		RB□ 1411	RB□ 1412	RB□ 2015	RB□ 2725
	e absorption mm)	5	6	7	11	12	15	25
	6	0.071	0.085	0.099	0.156	0.170	0.212	0.353
	10	0.196	0.236	0.274	0.432	0.471	0.589	0.982
	15	0.442	0.530	0.619	0.972	1.06	1.33	2.21
<u>-</u>	20	0.785	0.942	1.10	1.73	1.88	2.36	3.93
	25	1.23	1.47	1.72	2.70	2.95	3.68	6.14
	30	1.77	2.12	2.47	3.89	4.24	5.30	8.84
	40	3.14	3.77	4.40	6.91	7.54	9.42	15.7
(mm)	50	4.91	5.89	6.87	10.8	11.8	14.7	24.5
o	63	7.79	9.35	10.9	17.1	18.7	23.4	39.0
SIZE	80	12.6	15.1	17.6	27.6	30.2	37.7	62.8
Bore	100	19.6	23.6	27.5	43.2	47.1	58.9	98.2
Ω	125	30.7	36.8	43.0	67.5	73.6	92.0	153
	140	38.5	46.2	53.9	84.7	92.4	115	192
	160	50.3	60.3	70.4	111	121	151	251
	180	63.6	76.3	89.1	140	153	191	318
	200	78.5	94.2	110	173	188	236	393
	250	123	147	172	270	295	368	614
	300	177	212	247	389	424	530	884

■ Operating pressure other than 0.5 MPa: Multiply by the following coefficient.

Operating pressure (MPa)	0.1	0.2	0.3	0.4	0.5	0.6	0.7	0.8	0.9
Coefficient	0.2	0.4	0.6	0.8	1.0	1.2	1.4	1.6	1.8

## **Symbol**

Symbol	Specifications	Unit
d	Bore size	mm
Е	Absorbed energy	J
E <sub>1</sub>	Kinetic energy	٦
E <sub>2</sub>	Thrust energy	J
F <sub>1</sub>	Cylinder thrust	Ν
g	Acceleration of gravity (9.8)	m/s²
h	Dropping height	m
I (3)	Moment of inertia around the center of gravity	kg·m²
n	Operating frequency	cycle/min
р	Cylinder operation pressure	MPa
R	Distance between axis of cylinder and impact point	m
S	Shock absorber stroke	m
T	Torque	N⋅m
t	Ambient temperature	°C
υ	Collision speed	m/s
m	Impact object weight	kg
Ме	Corresponding weight of impact object	kg
ω	Angle speed	rad/s
μ	Friction coefficient	_

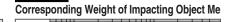
Data D

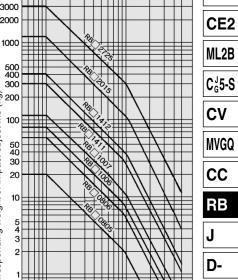
0.05 0.1

0.2 0.3 0.40.5

Collision speed υ (m/s)

2000









RE A

REC

C □ X

|C□Y

MQM

RHC

MK(2)

RS G

RS<sup>H</sup>

RZQ

MIS

CEP1

CE1



Data

10-18-4

0.3

0.1

**SMC** 

Load weight (kg)

10-18-5

## Series RB

## **<b>** Precautions

Be sure to read before handling. Refer to pages 10-24-3 to 10-24-6 for Safety Instructions and Actuator Precautions.

#### Selection

## 

1. Energy absorption

Select a model so that the aggregated energy of impact object should not exceed the maximum absorption energy. Otherwise, it could cause changes in properties or result in damaging the shock absorber.

2. Corresponding weight of impacting object

Make a model selection, so that the corresponding weight of impacting object does not exceed the allowable range. Pulsation will occur in buffer and deceleration force, thus making it difficult to absorb shock smoothly.

3. Collision speed

Use it in the conditions that collision speed is within the specified range. It could cause the changes in buffer characteristics or lead to damage a

## 🗥 Warning

1. Static load

Design the system, so that any other forces than the buffer capacity or impacts should not be applied to the piston rod which is stopped at the

## ∕!\ Caution

1. Maximum operating frequency

Design the system in the conditions under which it is not used at the frequency exceeding the specified maximum operating frequency. (But, the maximum operating frequency will vary depending on the absorbed energy.)

2. Stroke

The maximum absorption energy in the specifications cannot be exerted unless the full stroke is used for both Series RB and RBL.

3. Work surface of an impact object

The contact surface of the impact object with which the piston rod comes into contact must be highly rigid.

In the case without a cap, a high surface compression load is applied to the contact surface of the impact body with which the piston rod comes into contact. Therefore, the contact surface must be highly rigid (hardness of HRC35 or more).

4. Be aware of the return force of the impact object.

If used in a conveyor drive, after the shock absorber has absorbed energy, it could be pushed back by the spring that is built-in. For the spring force in the specifications, refer to the column (page 10-18-2).

5. Selection of size

As the number of operation proceeds, the maximum absorption energy of shock absorbers will be decreased by the following reasons such as abrasion, or deterioration, etc. of the internal working fluid. Taking this into consideration, selecting a size which is 20 to 40% affordable against the amount of absorption energy is recommended.

6. Drag characteristics

In general, the values of drag (reactive force generated during operation) generated by the operating speed will vary in hydraulic shock absorber. And then, by adopting "Porous orifice construction", the RB series can adapt to such this fast/slow speed and can absorb shock smoothly in a wide range of speed.

But, the speed reduction (speed reduction G) would be larger around the stroke terminal, depending upon the operating conditions. Please note that it might be encountered that stroke time is long, motion is not smooth, etc. If this would be a problem, we recommend that stroke amount should be restricted by using our optional component like

Including this case, if the data on operational status (stroke time, reactive force, deceleration, etc.) are required, please consult with SMC.

#### **Operating Environment**

## \Lambda Danger

1. Operation in an environment which requires explosion-proof

- When mounting in places where static electricity is accumulated, implement a distribution of electrical energy by grounding.
  Do not use the materials for buffer face which might cause to spark by

## 🗥 Warning

Do not use it in the vacuum state, which is substantially different from the atmospheric pressure (above sea level) and in the atmosphere under being pressurized.

#### 2. Using inside a clean room

Do not use the shock absorber in a clean room, as it could contaminate the clean room

## ∕!\ Caution

1. Temperature range

Do not use it, exceeding the specified allowable temperature range. Seal could be softened or hardened or worn out, or leading to leak a working fluid, deterioration, or impact characteristic changes.

2. Deterioration by atmosphere

Do not use in an atmosphere such as salt damage, sulfurous acid gas which makes the metal corroded, or having solvent, etc. which makes seal deteriorated.

3. Deterioration by ozone

Do not use it under the direct sunlight on the beach, or by the mercury lamp, or the ozone generator, because the rubber material will be deteriorated by ozone.

4. Cutting oil, water, blown dust

Do not use the product under the condition, where the liquid such as cutting oil, water, blown dust, solvent, etc. is exposed either directly or in atomized form to the piston rod, or where blown dust could be adhered around the piston rod. This could cause malfunction.

When vibrations are applied on impact objects, implement a secure guide on impact objects

## Mounting

## 🛝 Warning

1. Before performing installation, removal, or stroke adjustment, make sure to cut the power supply to the equipment and verify that the equipment has stopped.

2. Installation of protective cover

We recommend the protective cover should be installed in the case workers might be getting close during the operation.

3. The rigidity of the mounting frame must be taken into consideration If the mounting frame lacks strength, the shock absorber will vibrate after an impact, causing bearing wear and damage

Load on mounting plate can be calculated as follows.

Load on mounting plate  $N \cong 2$  E (Absorbed energy J)

## 🗥 Warning

1. Tightening torque of mounting nut should be as follows.

When threading on a mounting frame in order to mount a shock absorber directly, prepared hole dimensions are referred to the table below.

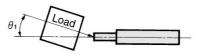
For tightening torque of a nut for shock absorber, kindly abide by the

If the tightening torque that is applied to the nut exceeds the value given below, the shock absorber itself could become damaged.

Model	RB(C)0805 RB(C)0806	RB(C)1006 RB(C)1007	RB(C)1411 RB(C)1412	RB(C)2015	RB(C)2725
O.D. thread (mm)	M8 x 1.0	M10 x 1.0	M14 x 1.5	M20 x 1.5	M27 x 1.5
Thread prepared bore (mm)	ø7.1 <sup>+ 0.1</sup>	ø9.1 <sup>+ 0.1</sup>	ø12.7 <sup>+ 0.1</sup>	ø18.7 <sup>+ 0.1</sup>	ø25.7 + 0.1
Tightening torque (N·m)	1.67	3.14	10.8	23.5	62.8

#### 2. Deviation of impact

The installation must be designed so that the impact body is perpendicular to the shock absorber's axial center. An angle of deviation that exceeds 3° will place an excessive load on the bearings, leading to oil leaks within a short period of operation.



Allowable eccentric angle  $\theta_1 < 3^{\circ}$ 

## Shock Absorber Series RB

## **A** Precautions

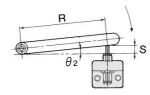
Be sure to read before handling. Refer to pages 10-24-3 to 10-24-6 for Safety Instructions and Actuator Precautions.

(mm)

#### Mounting

#### 3. Rotating angle

If rotating impacts are involved, the installation must be designed so that the direction in which the load is applied is perpendicular to the shock absorber's axial center. The allowable rotating angle until the stroke end must be  $\theta_2 < 3^{\circ}$ .



Allowable rotating eccentric angle  $\theta_2 < 3^\circ$ 

#### **Installation Conditions for Rotating Impact**

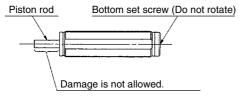
Model	<b>S</b> (Stroke)	(Allowable rotating angle)	R (Min. installation radius)
RB□□0805	5		96
RB□□0806	6		115
RB□□1006	6		115
RB□□1007	7	3°	134
<b>RB</b> □□1411	11		210
RB□□1412	12		229
RB□□2015	15		287
RB□□2725	25		478

Do not scratch the sliding portion of the piston rod or the outside threads of the outer tube.

Failure to observe this precaution could scratch or gouge the sliding potion of the piston rod, or damage the seals, which could lead to oil leakage and malfunction. Furthermore, damage to outside threaded portion of the outer tube could prevent the shock absorber from being mounted onto the frame, or its internal components could deform, leading to a malfunction.

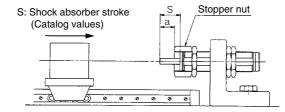
5. Never turn the screw on the bottom of the body.

This is not an adjusting screw. Turning it could result in oil leakage.



Adjust the stopping time through the use of the stopper nut, as follows:

Control the stopping time of the impact object by turning the stopper nut in or out (thus changing length "a"). After establishing the stopper nut position, use a hexagon nut to secure the stopper nut in place.



#### **Maintenance**

## **⚠** Caution

- 1. Check the mounting nut is not loosen.
- The shock absorber could become damaged if it is used in a loose state.
- 2. Pay attention to any abnormal impact sounds or vibrations. If the impact sounds or vibrations have become abnormally high, the shock absorber may have reached the end of its service life. If this is the case, replace the shock absorber. If use is continued in this state, it could lead to equipment damage.
- 3. Confirm that abnormality, oil leakage, etc. in the outward surface. When a large amount of oil is leaking, replace the product, because it is believed to be happening something wrong with it. If it keeps on using, it may cause to break the equipment which is mounted by this product.
- 4. Inspect the cap for any cracks or wear. If the shock absorber comes with a cap, the cap could wear first. To prevent damage to the impact object, replace the cap often.

REA

REC

C□X

C□Y

MQ M

RHC

MK(2)

RS<sup>Q</sup><sub>G</sub>

RS<sup>H</sup>

RZQ

MI<sub>s</sub>

CEP1

\_\_\_\_

CE2

ML2B

C<sub>G</sub>5-S

CV

MVGQ

CC RB

J

D-

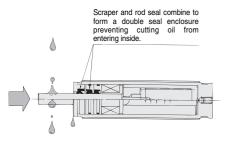
-X 20-

Data



# Shock Absorber: Coolant Resistant Type Series RBL

Can be operated in an environments exposed to non-water soluble cutting oil. (Mainly JIS Class 1 equivalent)



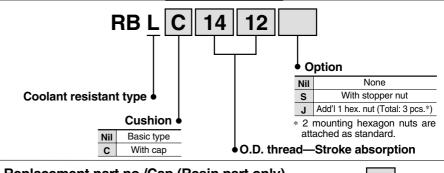


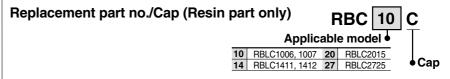
#### **Specifications**

Opecinica									
Mode	el Basic type	RBL1006	RBL1007	RBL1411	RBL1412	RBL2015	RBL2725		
Specifications	With cap	RBLC1006	RBLC1007	RBLC1411	RBLC1412	RBLC2015	RBLC2725		
Max. energy a	bsorption (J)	3.92	5.88	14.7	19.6	58.8	147		
Stroke absorp	tion (mm)	6	7	11	12	15	25		
Collision spee	d (m/s)		0.05 to 5						
Max. operating frequ (cycle/min)	ency*	70	70	45	45	25	10		
Max. allowabl	e thrust (N)	422	422	814	814	1961	2942		
Allowable tempera	ature range (°C)	-10 to 80							
Effective atmo	sphere		Non-water soluble cutting oil						
Spring force	Extended	4.22	4.22	8.73	8.73	11.57	22.16		
(N)	Retracted	6.18	6.86	14.12	14.61	17.65	38.05		
Mainlet (a)	Basic type	26	26	70	70	150	365		
Weight (g)	With cap	28	28	75	75	165	410		

<sup>\*</sup> It denotes the values at the maximum energy absorption per one cycle. Max. operation cycle/min can increase in proportion to energy absorption.

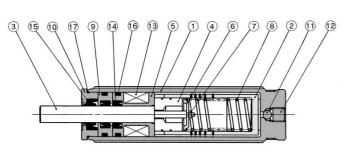
## **How to Order**





Cap cannot be mounted for basic type. Please place an order with cap type from the beginning.

## Construction



#### **Component Parts**

	•		
No.	Description	Material	Treatment
1	Outer tube	Rolled steel	Gray coated
2	Inner tube	Special steel	Heat treated
3	Piston rod	Special steel	Electroless nickel plated
4	Piston	Special steel	Heat treated
(5)	Bearing	Special bearing material	
6	Spring guide	Carbon steel	Zinc chromated
7	Lock ring	Copper	
8	Return spring	Piano wire	Zinc chromated
9	Seal holder	Copper alloy	
10	Stopper	Carbon steel	Zinc chromated
11)	Steel ball	Bearing steel	
12	Set screw	Special steel	
13	Accumulator	NBR	Foam rubber
14)	Rod seal	NBR	
15	Scraper	NBR	
16	Gasket	NBR	
17	Gasket	NBR	Only RBL(C)2015, 2725



## Shock Absorber: Coolant Resistant Type Series RBL

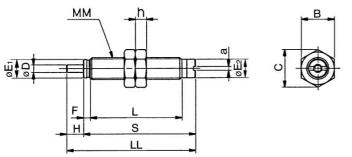
## **Dimensions**

Basic type

**RBL1006** 

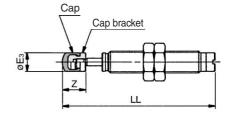
**RBL1007** 

## Basic type: RBL1006, RBL1007



## With cap: RBLC1006, RBLC1007

\* Other dimensions are the same as the basic type.



RE A

**REC** 

**C**□X

**C**□Y

MQ M

**RHC** 

Hexagon nut

С

16.2

16.2

h

В

14

14

10

10

MK(2)

RS<sub>G</sub>

RS<sub>A</sub>

**RZQ** 

MIS CEP1

CE1

CE<sub>2</sub>

ML2B

C<sub>G</sub>5-S

CV

MVGQ

CC RB

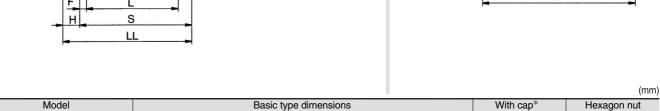
J

D-

-X

20-

Data



43.8 57.5

43.8 58.5

Basic type dimensions

а

1.4

1.4

Note) L, LL and S dimensions of RBL(C)1007/1006 are different from those of RB(C)1007/1006.

8.8

8.8

3

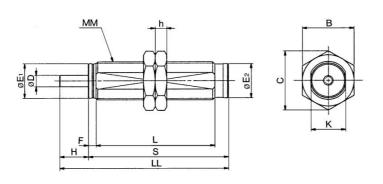
3

## Basic type: RBL1411, RBL1412, RBL2015, RBL2725

With cap

**RBLC1006** 

**RBLC1007** 



8.6

8.6

2.7

2.7

## With cap: RBLC1411, RBLC1412 RBLC2015, RBLC2725

Eз

8.7

S

51.5

51.5

M10 x 1.0

M10 x 1.0

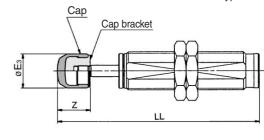
With cap

LL

67.5

68.5

\* Other dimensions are the same as the basic type.

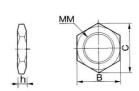


Mo	Basic type dimensions						With cap*		Hexagon nut		nut						
Basic type	With cap	D	E <sub>1</sub>	E <sub>2</sub>	F	Н	K	L	LL	MM	S	E₃	LL	Z	В	С	h
RBL1411	RBLC1411	5	12.2	12	3.5	11	12	63.6	83.1	M14 x 1.5	72.1	12	96.6	13.5	19	21.9	6
RBL1412	RBLC1412	5	12.2	12	3.5	12	12	63.6	84.1	M14 x 1.5	72.1	12	97.6	13.5	19	21.9	6
RBL2015	RBLC2015	6	18.2	18	4	15	18	62.2	88.2	M20 x 1.5	73.2	18	105.2	17	27	31.2	6
RBL2725	RBLC2725	8	25.2	25	5	25	25	91.5	129.5	M27 x 1.5	104.5	25	152.5	23	36	41.6	6

Note) L, LL and S dimensions of RBL(C)1007/1006 are different from those of RB(C)1007/1006.

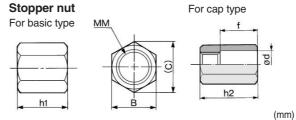
## **Hexagon Nut**

(2 pcs. standard equipment)



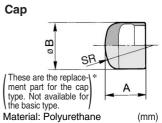
				(mm
Part no.	D	imensi	ons	
rait iio.	MM	h	В	С
RB10J	M10 x 1.0	4	14	16.2
RB14J	M14 x 1.5	6	19	21.9
RB20J	M20 x 1.5	6	27	31.2
RB27J	M27 x 1.5	6	36	41.6

## **Option**



Par	t no.		Dimensions							
Basic type	With cap	В	С	h1	h2	MM	d	f		
RB10S	RBC10S	14	16.2	8	23	M10 x 1.0	11	15		
<b>RB14S</b>	RBC14S	19	21.9	11	31	M14 x 1.5	15	20		
RB20S	RBC20S	27	31.2	16	40	M20 x 1.5	23	25		
RB27S	RBC27S	36	41.6	22	51	M27 x 1.5	32	33		

## **Replacement Parts**



	•			
Part no.	Di	mensio	ns	
raitiio.	Α	В	SR	
RBC10C	9	8.7	7.5	
RBC14C	12.5	12	10	
RBC20C	16	18	20	
RBC27C	21	25	25	



## **Shock Absorber: Short Type**

## Series RBQ

#### Allowable eccentric angle is 5°

Ideal for absorption of rotating energy

#### Specifications

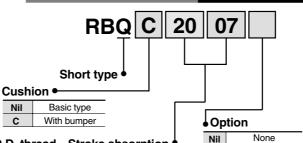
Opcomeation								
Model	Basic type	RBQ1604	RBQ2007	RBQ2508	RBQ3009	RBQ3213		
Specifications	With bumper	RBQC1604	RBQC2007	RBQC2508	RBQC3009	RBQC3213		
Max. energy abso	orption (J)	1.96	11.8	19.6	33.3	49.0		
Stroke absorption	(mm)	4	7	8	8.5	13		
Collision speed (n	n/s)	0.05 to 3						
Max. operating frequency	/* (cycle/min)	60	60	45	45	30		
Max. allowable th	rust (N)	294	490	686	981	1177		
Ambient temperat	ure (C°)	-10 to 80						
On the or force (NI)	Extended	6.08	12.75	15.69	21.57	24.52		
Spring force (N)	Retracted	13.45	27.75	37.85	44.23	54.23		
Weight (g)		28	60	110	182	240		
Option/Stopper nu	ut	RBQ16S	RB20S	RBQ25S	RBQ30S	RBQ32S		

<sup>\*</sup>It denotes the values at the maximum energy absorption per one cycle. Therefore, the operating frequency can be increased according to the energy absorption.



With bumper Series RBQC

Basic type Series RBQ



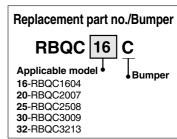
O.D. thread—Stroke absorption Bumper cannot be mounted for basic type. Please place an order with bumper type from the beginning.

## How to Order

With stopper nut

Add'l 1 of hex. nut

(Total: 3 pcs.\*)



2 mounting hexagon nuts are attached as standard.

#### Construction

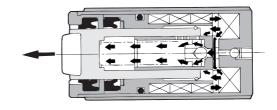
# At impact (3)

An impact object that strikes against the piston rod end pressurizes oil inside the piston. Thus, pressurized oil jets out through the orifice inside the piston, thereby generating hydraulic resistance to absorb the energy of the impacting object.

The oil jetted out through the orifice is collected inside the outer tube by means of the stretching action of the accumulator.

#### At returning

s



When the impact object is removed, the return spring pushes out the piston rod, and negative pressure, generated at the same time, opens the check ball to permit oil to return to the shock absorber ready for the next impact.

## **Component Parts**

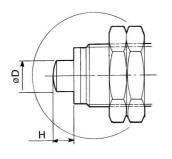
No.	Description	Material	Treatment	
1	Outer tube	Rolled steel	Black nickel plated	
2	Piston rod	Special steel	Heat treated, Hard chrome plated	
3	Piston	Special steel	Heat treated	
4	Bearing	Special bearing material		
(5)	Return spring	Piano wire	Zinc chromated	
6	Stopper	Carbon steel	Zinc chromated	

No.	Description	Material	Treatment
7	Check ball	Bearing steel	
8	Accumulator	Fluoro rubber	Foam rubber
9	Rod seal	NBR	
10	Scraper	NBR	
11)	Bumper	Polyurethane	Only with bumper

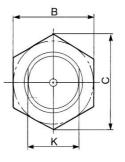


## Shock Absorber: Short Type Series RBQ

## **Dimensions**



MM Bumper



**Series RBQ Basic type** 

With bumper

**RBQC1604** 

**RBQC2007** 

**RBQC2508** 

**RBQC3009** 

**RBQC3213** 

D

6

10

12

18

Ε

14.2

18.2

23.2

28.2

30.2

(mm)

С

25.4

31.2

47.3

47.3

37

В

22

27

32

41

41

Model

**Series RBQC** With bumper

Κ

14

18

23

28

30

Shock absorber

G

9

10

12

13

(mm)

6

6

6

6

6

Hexagon nut

С

25.4

31.2

47.3

47.3

37

В

22

27

32

41

41

MK(2)

RS G

RE A

**REC** 

**C**□X

C 🗆 Y

MQ M

**RHC** 

RSA A

**RZQ** 

MIS

CEP1

CE1

CE<sub>2</sub>

ML2B

C<sub>G</sub>5-S

(mm)

CV

MVGQ

CC

RB

J

D-

-X 20-

Data

## **Hexagon Nut**

Basic type

**RBQ1604** 

**RBQ2007** 

**RBQ2508** 

**RBQ3009** 

**RBQ3213** 

(2 pcs. standard equipment)



Part no.

RBQ16J

**RB20J** (1)

RBQ25J

RBQ30J

RBQ32J



h

6

6

6

6

MM

M16 x 1.5

M20 x 1.5

M25 x 1.5

M30 x 1.5

M32 x 1.5 6

Note 1) In the case of RB20J, RB and RBQ are

## **Option**

3.5

4

4

5

4

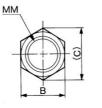
8

13

8.5

## Stopper nut





LL

31

52

76

44.5

61.5

Material:	Carbon	steel

Material: Carbon steel				(mm)	
Part no.	В	С	h1	MM	
RBQ16S	22	25.4	12	M16 x 1.5	
RB20S (2)	27	31.2	16	M20 x 1.5	
RBQ25S	32	37	18	M25 x 1.5	
RBQ30S	41	47.3	20	M30 x 1.5	
RBQ32S	41	47.3	25	M32 x 1.5	

Note 2) In the case of RB20S, RB and RBQ are common.

## **Replacement Parts**

s

27

44

53

63

37.5

### **Bumper**

ММ

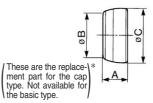
M16 x 1.5

M20 x 1.5

M25 x 1.5

M30 x 1.5

M32 x 1.5



Material:	Polyurethane

Part no.	Α	В	С
RBQC16C	3.5	4	4.7
RBQC20C	4.5	8	8.3
RBQC25C	5	8.3	9.3
RBQC30C	6	11.3	12.4
RBQC32C	6.6	13.1	14.4

**SMC** 

10-18-11