6ES7512-1DK01-0AB0

## **Data sheet**



SIMATIC DP, CPU 1512SP-1 PN for ET 200SP, Central processing unit with Work memory 200 KB for program and 1 MB for data, 1st interface: PROFINET IRT with 3-port switch, 48 ns bit performance, SIMATIC Memory Card required, BusAdapter required for Port 1 and 2

General information	
Product type designation	CPU 1512SP-1 PN
HW functional status	FS05
Firmware version	V2.9
Product function	
• I&M data	Yes; I&M0 to I&M3
<ul> <li>Module swapping during operation (hot swapping)</li> </ul>	Yes; Multi-hot swapping
Isochronous mode	Yes; Only with PROFINET; with minimum OB 6x cycle of 625 µs
Engineering with	
<ul> <li>STEP 7 TIA Portal configurable/integrated from version</li> </ul>	V17 (FW V2.9) / V13 SP1 Update 4 (FW V1.8) or higher
Configuration control	
via dataset	Yes
Control elements	
Mode selector switch	1
Supply voltage	
Rated value (DC)	24 V
permissible range, lower limit (DC)	19.2 V
permissible range, upper limit (DC)	28.8 V
Reverse polarity protection	Yes
Mains buffering	
<ul> <li>Mains/voltage failure stored energy time</li> </ul>	5 ms
Input current	
Current consumption (rated value)	0.6 A
Current consumption, max.	0.9 A
Inrush current, max.	4.7 A; Rated value
l²t	0.14 A <sup>2</sup> ·s
Power	
Infeed power to the backplane bus	8.75 W
Power loss	
Power loss, typ.	5.6 W
Memory	
Number of slots for SIMATIC memory card	1
SIMATIC memory card required	Yes
Work memory	
• integrated (for program)	200 kbyte
<ul><li>integrated (for data)</li></ul>	1 Mbyte
Load memory	
<ul> <li>Plug-in (SIMATIC Memory Card), max.</li> </ul>	32 Gbyte

Backup	
maintenance-free	Yes
CPU processing times	165
for bit operations, typ.	48 ns
for word operations, typ.	58 ns
for fixed point arithmetic, typ.	77 ns
for floating point arithmetic, typ.	307 ns
CPU-blocks	307 118
	4 000: Blocks (OR, ER, EC, DR) and LIDTs
Number of elements (total)	4 000; Blocks (OB, FB, FC, DB) and UDTs
DB • Number range	1 60 000; subdivided into: number range that can be used by the
Number range	1 60 999; subdivided into: number range that can be used by the user: 1 59 999, and number range of DBs created via SFC 86: 60 000 60 999
• Size, max.	1 Mbyte; For DBs with absolute addressing, the max. size is 64 KB
FB	
Number range	0 65 535
• Size, max.	200 kbyte
FC	
Number range	0 65 535
• Size, max.	200 kbyte
ОВ	
• Size, max.	200 kbyte
<ul> <li>Number of free cycle OBs</li> </ul>	100
Number of time alarm OBs	20
<ul> <li>Number of delay alarm OBs</li> </ul>	20
Number of cyclic interrupt OBs	20; With minimum OB 3x cycle of 500 µs
Number of process alarm OBs	50
Number of DPV1 alarm OBs	3
Number of isochronous mode OBs	1
Number of technology synchronous alarm OBs	2
Number of startup OBs	100
Number of startup OBs     Number of asynchronous error OBs	4
Number of asynchronous error OBs	2
Number of synchronous error OBs     Number of diagnostic alarm OBs	1
	-
Nesting depth	24
• per priority class	Z4
Counters, timers and their retentivity	
S7 counter	
• Number	2 048
Retentivity	
— adjustable	Yes
IEC counter	
Number	Any (only limited by the main memory)
Retentivity	
— adjustable	Yes
S7 times	
Number	2 048
Retentivity	
— adjustable	Yes
IEC timer	
Number	Any (only limited by the main memory)
Retentivity	
— adjustable	Yes
Data areas and their retentivity	
Retentive data area (incl. timers, counters, flags), max.	128 kbyte; Available retentive memory for bit memories, timers, counters, DBs, and technology data (axes): 88 KB
Flag	
• Size, max.	16 kbyte
Number of clock memories	8; 8 clock memory bit, grouped into one clock memory byte
Data blocks	

Retentivity adjustable	Yes
Retentivity adjustable     Retentivity preset	No
Local data	NO
per priority class, max.	64 kbyte; max. 16 KB per block
Address area	OF ROYCO, MICK. TO NO POLICION
Number of IO modules	2 048; max. number of modules / submodules
I/O address area	2 048, max. number of modules / submodules
• Inputs	32 kbyte; All inputs are in the process image
Outputs	32 kbyte; All outputs are in the process image
per integrated IO subsystem	52 kbyte, All outputs are in the process image
— Inputs (volume)	8 kbyte
— Outputs (volume)	8 kbyte
per CM/CP	o noyte
— Inputs (volume)	8 kbyte
— Outputs (volume)	8 kbyte
Subprocess images	o hoyte
Number of subprocess images, max.	32
Address space per module	52
Address space per module, max.	288 byte; For input and output data respectively
Address space per module, max.  Address space per station	200 byte, 1 or imput and output data respectively
Address space per station, max.	2 560 byte; for central inputs and outputs; depending on configuration; 2
Address space per station, max.	048 bytes for ET 200SP modules + 512 bytes for ET 200AL modules
Hardware configuration	
Number of distributed IO systems	32; A distributed I/O system is characterized not only by the integration of distributed I/O via PROFINET or PROFIBUS communication modules, but also by the connection of I/O via AS-i master modules or links (e.g. IE/PB-Link)
Number of DP masters	
● Via CM	1
Number of IO Controllers	
• integrated	1
• Via CM	0
Rack	
Modules per rack, max.	80; CPU + 64 modules + server module (mounting width max. 1 m) + 16 ET 200AL modules
<ul> <li>Quantity of operable ET 200SP modules, max.</li> </ul>	64
<ul> <li>Quantity of operable ET 200AL modules, max.</li> </ul>	16
<ul> <li>Number of lines, max.</li> </ul>	1
PtP CM	
Number of PtP CMs	the number of connectable PtP CMs is only limited by the number of available slots
Time of day	
Clock	
• Type	Hardware clock
Backup time	6 wk; At 40 °C ambient temperature, typically
<ul> <li>Deviation per day, max.</li> </ul>	10 s; Typ.: 2 s
Operating hours counter	
Number	16
Clock synchronization	
• supported	Yes
• to DP, master	Yes; Via CM DP module
• to DP, slave	Yes; Via CM DP module
• in AS, master	Yes
• in AS, slave	Yes
<ul> <li>on Ethernet via NTP</li> </ul>	Yes
Interfaces	
Number of PROFINET interfaces	1
Number of PROFIBUS interfaces	1; Via CM DP module
Optical interface	Yes; via BusAdapter
1. Interface	
Interface types	

• RJ 45 (Ethernet) Yes; X1 P3; opt. X1 P1 and X1 P2 via BusAdapter BA 2x RJ45 Number of ports 3; 1. integr. + 2. via BusAdapter integrated switch Yes • BusAdapter (PROFINET) Yes; compatible BusAdapters: BA 2x RJ45, BA 2x M12, BA 2x FC, BA 2x LC, BA LC/RJ45, BA LC/FC, BA 2x SCRJ, BA SCRJ/RJ45, BA SCRJ/FC Protocols Yes; IPv4 IP protocol PROFINET IO Controller Yes • PROFINET IO Device Yes • SIMATIC communication Yes • Open IE communication Yes; Optionally also encrypted Web server Media redundancy Yes; MRP Automanager according to IEC 62439-2 Edition 2.0 **PROFINET IO Controller** Services — PG/OP communication Yes Yes Isochronous mode Yes; Requirement: IRT and isochronous mode (MRPD optional) - Direct data exchange - IRT - PROFlenergy Yes; per user program - Prioritized startup Yes; Max. 32 PROFINET devices - Number of connectable IO Devices, max. 128; In total, up to 512 distributed I/O devices can be connected via ASi, PROFIBUS or PROFINET - Of which IO devices with IRT, max. 64 128 - Number of connectable IO Devices for RT, max. 128 - of which in line, max. - Number of IO Devices that can be 8; in total across all interfaces simultaneously activated/deactivated, max. - Number of IO Devices per tool, max. 8 - Updating times The minimum value of the update time also depends on communication share set for PROFINET IO, on the number of IO devices, and on the quantity of configured user data Update time for IRT — for send cycle of 250 µs 250 µs to 4 ms; Note: In the case of IRT with isochronous mode, the minimum update time of 500 µs of the isochronous OB is decisive — for send cycle of 500 µs 500 µs to 8 ms - for send cycle of 1 ms 1 ms to 16 ms - for send cycle of 2 ms 2 ms to 32 ms - for send cycle of 4 ms 4 ms to 64 ms — With IRT and parameterization of "odd" send Update time = set "odd" send clock (any multiple of 125 μs: 375 μs, 625 cycles μs ... 3 875 μs) Update time for RT — for send cycle of 250 µs 250 µs to 128 ms - for send cycle of 500 μs 500 μs to 256 ms - for send cycle of 1 ms 1 ms to 512 ms - for send cycle of 2 ms 2 ms to 512 ms — for send cycle of 4 ms 4 ms to 512 ms **PROFINET IO Device** Services - PG/OP communication Yes Isochronous mode Nο — IRT Yes — PROFlenergy Yes; per user program - Shared device Yes - Number of IO Controllers with shared device, 4 - activation/deactivation of I-devices Yes; per user program - Asset management record Yes; per user program 2. Interface Interface types

- DC 405	Van Via CM DD madula
• RS 485	Yes; Via CM DP module
Number of ports  Protocols	1
Protocols  - DDOFIDUS DD mostor	Voo
PROFIBUS DP master	Yes
PROFIBUS DP slave	Yes
SIMATIC communication	Yes
PROFIBUS DP master	10.00
Number of connections, max.	48; Of which 4 each reserved for ES and HMI
<ul> <li>Number of DP slaves, max.</li> </ul>	125; In total, up to 512 distributed I/O devices can be connected via AS-i, PROFIBUS or PROFINET
Services	I, FROFIBOS DI FROFINET
— PG/OP communication	Voa
	Yes
— Equidistance	No
— Isochronous mode	No
Activation/deactivation of DP slaves	Yes
Interface types	
RJ 45 (Ethernet)	
• 100 Mbps	Yes
<ul> <li>Autonegotiation</li> </ul>	Yes
<ul> <li>Autocrossing</li> </ul>	Yes
Industrial Ethernet status LED	Yes
RS 485	
Transmission rate, max.	12 Mbit/s
Protocols	
PROFIsafe	No
Number of connections	
Number of connections, max.	128; via integrated interfaces of the CPU and connected CPs / CMs
Number of connections reserved for ES/HMI/web	10
Number of connections via integrated interfaces	88
Number of connections per CP/CM	32
Number of S7 routing paths	16
Redundancy mode	10
H-Sync forwarding	Yes
Media redundancy	165
·	Voca only via Dua Adapter
— Media redundancy	Yes; only via BusAdapter
— MRP	Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager; MRP Client
- MRP interconnection, supported	Yes; as MRP ring node according to IEC 62439-2 Edition 3.0
— MRPD	Yes; Requirement: IRT
	200 ms; For MRP, bumpless for MRPD
Switchover time on line break, typ.	
— Number of stations in the ring, max.	50
SIMATIC communication  • PG/OP communication	Voc: openintian with TLC 1/4.2 are calcuted
	Yes; encryption with TLS V1.3 pre-selected
• S7 routing	Yes
Data record routing	Yes
S7 communication, as server	Yes
S7 communication, as client	Yes
User data per job, max.	See online help (S7 communication, user data size)
Open IE communication	
• TCP/IP	Yes
<ul><li>Data length, max.</li></ul>	64 kbyte
<ul> <li>several passive connections per port,</li> </ul>	Yes
supported	W.
• ISO-on-TCP (RFC1006)	Yes
— Data length, max.	64 kbyte
• UDP	Yes
— Data length, max.	2 kbyte; 1 472 bytes for UDP broadcast
<ul><li>UDP multicast</li></ul>	Yes; Max. 5 multicast circuits
• DHCP	Yes
• DNS	Yes
• SNMP	Yes

• DCP	Yes
• LLDP	Yes
Encryption	Yes; Optional
Web server	
• HTTP	Yes; Standard and user pages
• HTTPS	Yes; Standard and user pages
OPC UA	
Runtime license required	Yes; "Small" license required
OPC UA Client	Yes
<ul> <li>Application authentication</li> </ul>	Yes
— Security policies	Available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256
User authentication	"anonymous" or by user name & password
<ul><li>Number of connections, max.</li></ul>	4
<ul> <li>Number of nodes of the client interfaces, max.</li> </ul>	1 000
<ul> <li>Number of elements for one call of OPC_UA_NodeGetHandleList/OPC_UA_ReadList/C max.</li> </ul>	300
Number of elements for one call of OPC UA NameSpaceGetIndexList, max.	20
Number of elements for one call of OPC_UA_MethodGetHandleList, max.	100
Number of simultaneous calls of the client	1
instructions per connection (except OPC_UA_ReadList,OPC_UA_WriteList,OPC_UA_M max.	
Number of simultaneous calls of the client instructions	5
OPC_UA_ReadList,OPC_UA_WriteList and OPC_UA_MethodCall, max.	
<ul> <li>Number of registerable nodes, max.</li> </ul>	5 000
<ul> <li>Number of registerable method calls of OPC_UA_MethodCall, max.</li> </ul>	100
<ul><li>— Number of inputs/outputs when calling OPC_UA_MethodCall, max.</li></ul>	20
OPC UA Server	Yes; Data access (read, write, subscribe), method call, custom address space
<ul><li>— Application authentication</li><li>— Security policies</li></ul>	Yes Available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256
<ul> <li>User authentication</li> </ul>	"anonymous" or by user name & password
<ul> <li>— GDS support (certificate management)</li> </ul>	Yes
<ul><li>Number of sessions, max.</li></ul>	32
<ul> <li>Number of accessible variables, max.</li> </ul>	50 000
<ul> <li>Number of registerable nodes, max.</li> </ul>	10 000
<ul> <li>Number of subscriptions per session, max.</li> </ul>	20
— Sampling interval, min.	100 ms
<ul><li>— Publishing interval, min.</li></ul>	500 ms
<ul> <li>Number of server methods, max.</li> </ul>	20
<ul> <li>Number of inputs/outputs per server method, max.</li> </ul>	20
Number of monitored items, max.	1 000; for 1 s sampling interval and 1 s send interval
— Number of server interfaces, max.	10 of each "Server interfaces" / "Companion specification" type and 20 of the type "Reference namespace"
Number of nodes for user-defined server interfaces, max.	1 000
Alarms and Conditions	Yes
— Number of program alarms	100
Number of alarms for system diagnostics	50
Further protocols	V. MORRIJO TOR
MODBUS	Yes; MODBUS TCP
S7 message functions	
Number of login stations for message functions, max.	32
Program alarms	Yes

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Number of configurable program messages, max.	5 000; Program messages are generated by the "Program_Alarm" block, ProDiag or GRAPH
Number of loadable program messages in RUN, max.	2 500
Number of simultaneously active program alarms	
<ul> <li>Number of program alarms</li> </ul>	600
<ul> <li>Number of alarms for system diagnostics</li> </ul>	100
<ul> <li>Number of alarms for motion technology objects</li> </ul>	80
Test commissioning functions	
Joint commission (Team Engineering)	Yes; Parallel online access possible for up to 5 engineering systems
Status block	Yes; Up to 8 simultaneously (in total across all ES clients)
Single step	No
Number of breakpoints	8
Status/control	
Status/control variable	Yes
Variables	Inputs/outputs, memory bits, DBs, distributed I/Os, timers, counters
Number of variables, max.	inpute outpute, memory site, sse, distributed if se, amore, seamers
of which status variables, max.	200; per job
of which status variables, max.  — of which control variables, max.	
Forcing	200; per job
•	Yes
<ul><li>Forcing</li><li>Forcing, variables</li></ul>	
	Peripheral inputs/outputs
Number of variables, max.	200
Diagnostic buffer	v
• present	Yes
<ul> <li>Number of entries, max.</li> </ul>	1 000
— of which powerfail-proof	500
Traces	
Number of configurable Traces	4; Up to 512 KB of data per trace are possible
Interrupts/diagnostics/status information	
Diagnostics indication LED	
RUN/STOP LED	Yes
• ERROR LED	Yes
MAINT LED	Yes
<ul> <li>Monitoring of the supply voltage (PWR-LED)</li> </ul>	Yes
Connection display LINK TX/RX	Yes
Supported technology objects	
Motion Control	Yes; Note: The number of technology objects affects the cycle time of
Modell Control	the PLC program; selection guide via the TIA Selection Tool
Number of available Motion Control resources for technology objects.	800
technology objects	
technology objects • Required Motion Control resources	800
technology objects  ● Required Motion Control resources  — per speed-controlled axis	800 40
technology objects  Required Motion Control resources  — per speed-controlled axis  — per positioning axis	800 40 80
technology objects  Required Motion Control resources  — per speed-controlled axis  — per positioning axis  — per synchronous axis	800 40 80 160
technology objects  Required Motion Control resources  — per speed-controlled axis  — per positioning axis	800 40 80 160 80
technology objects  Required Motion Control resources  — per speed-controlled axis  — per positioning axis  — per synchronous axis	800 40 80 160
technology objects  Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder	800 40 80 160 80
technology objects  Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam	800 40 80 160 80 20
technology objects  Required Motion Control resources  — per speed-controlled axis  — per positioning axis  — per synchronous axis  — per external encoder  — per output cam  — per cam track	800 40 80 160 80 20 160
technology objects  Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe	800 40 80 160 80 20 160
technology objects  Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe  Positioning axis — Number of positioning axes at motion control	800 40 80 160 80 20 160 40
technology objects  Required Motion Control resources  — per speed-controlled axis  — per positioning axis  — per synchronous axis  — per external encoder  — per output cam  — per cam track  — per probe  Positioning axis  — Number of positioning axes at motion control cycle of 4 ms (typical value)  — Number of positioning axes at motion control	800 40 80 160 80 20 160 40
technology objects  Required Motion Control resources  — per speed-controlled axis  — per positioning axis  — per synchronous axis  — per external encoder  — per output cam  — per cam track  — per probe  Positioning axis  — Number of positioning axes at motion control cycle of 4 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller	800 40 80 160 80 20 160 40
technology objects  Required Motion Control resources  — per speed-controlled axis  — per positioning axis  — per synchronous axis  — per external encoder  — per output cam  — per cam track  — per probe  Positioning axis  — Number of positioning axes at motion control cycle of 4 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  PID_Compact	40 80 160 80 20 160 40 5 10  Yes; Universal PID controller with integrated optimization
technology objects  Required Motion Control resources  — per speed-controlled axis  — per positioning axis  — per synchronous axis  — per external encoder  — per output cam  — per cam track  — per probe  Positioning axis  — Number of positioning axes at motion control cycle of 4 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  PID_Compact  PID_Step	40 80 160 80 20 160 40  5 10  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves
technology objects  Required Motion Control resources  — per speed-controlled axis  — per positioning axis  — per synchronous axis  — per external encoder  — per output cam  — per cam track  — per probe  Positioning axis  — Number of positioning axes at motion control cycle of 4 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  PID_Compact  PID_Step  PID-Temp	40 80 160 80 20 160 40 5 10  Yes; Universal PID controller with integrated optimization
technology objects  Required Motion Control resources  — per speed-controlled axis  — per positioning axis  — per synchronous axis  — per external encoder  — per output cam  — per cam track  — per probe  Positioning axis  — Number of positioning axes at motion control cycle of 4 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  PID_Compact  PID_Temp  Counting and measuring	40 80 160 80 20 160 40  5  10  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature
technology objects  Required Motion Control resources  — per speed-controlled axis  — per positioning axis  — per synchronous axis  — per external encoder  — per output cam  — per cam track  — per probe  Positioning axis  — Number of positioning axes at motion control cycle of 4 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  PID_Compact  PID_Step  PID-Temp	40 80 160 80 20 160 40  5 10  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves

<ul> <li>horizontal installation, min.</li> </ul>	-25 °C; No condensation
horizontal installation, max.	60 °C
vertical installation, min.	-25 °C; No condensation
vertical installation, max.	50 °C
Altitude during operation relating to sea level	
Installation altitude above sea level, max.	5 000 m; Restrictions for installation altitudes > 2 000 m, see manual
configuration / header	5 000 HI, Noothelion of Motanation attitudes - 2 000 HI, occ manati
configuration / programming / header	
Programming language	
— LAD	Yes
— FBD	Yes
— STL	Yes
— SCL	Yes
— GRAPH	Yes
Know-how protection	
User program protection/password protection	Yes
Copy protection	Yes
Block protection	Yes
Access protection	
<ul> <li>protection of confidential configuration data</li> </ul>	Yes
<ul> <li>Protection level: Write protection</li> </ul>	Yes
<ul> <li>Protection level: Read/write protection</li> </ul>	Yes
<ul> <li>Protection level: Complete protection</li> </ul>	Yes
Dimensions	
Width	100 mm
Height	117 mm
Depth	75 mm
Weights	
Weight, approx.	310 g

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last modified: